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# Set-theoretical solutions to the Yang-Baxter Relation from factorization of matrix polynomials and $\theta$-functions 

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## Introduction

The Yang-Baxter relation plays a central role in two-dimensional Quantum Field Theory. This relation involves a linear operator $R: V \otimes V \rightarrow V \otimes V$, where $V$ is a vector space, and has the form

$$
R^{12} R^{13} R^{23}=R^{23} R^{13} R^{12}
$$

in $\operatorname{End}(V \otimes V \otimes V)$, where $R^{i j}$ means $R$ acting in the $i$-th and $j$-th components. In the paper [12] V. Drinfeld suggested to study set-theoretical solutions of this relation, i.e. solutions given by a map $R: X \times X \rightarrow X \times X$, where $X$ is a given set. Moreover, if $X$ is an algebraic manifold, then $R$ may be a rational map. The general theory of set-theoretical solutions to the quantum Yang-Baxter relation was developed in [11, 13]. Various examples were constructed in [10, 11, 13]. In this paper we construct such solutions from decompositions of matrix polynomials and $\theta$-functions. These solutions arise from the decompositions "in different order". We also construct a "local action of the symmetric group" in these cases, generalizations of the action of the symmetric group $S N$ on $X^{N}$ given by the set-theoretical solution. The structure of the paper is as follows. In $\S \mathbf{1}$ we give basic definitions. In $\S \mathbf{2}$ we introduce a set-theoretical solution arising from the factorization of matrix polynomials. In $\S \mathbf{3}$ we introduce a set-theoretical solution arising from matrix $\theta$-functions.

For a given set-theoretical solution of the quantum Yang-Baxter relation one can define a twisted Yang-Baxter relation with the set of spectral parameters $X$ (see [14] and (3) of this paper). The corresponding twisted $R$-matrix describes a scattering of two "particles" such that the spectral parameters change after scattering according to a given set-theoretical solution. Moreover, one can define a generalized star-triangle relation for a given local action of the symmetric group (see [14]). The examples of twisted $R$-matrices as well as the solutions of the generalized star-triangle relation were found in [4] as intertwiners of cyclic representations and their tensor products of the algebra of monodromy matrices of the six-vertex model at roots of unity [3]. These solutions are natural generalizations of the one from the chiral Potts model $[1,2,3]$. Other examples were found in [9] for the relativistic Toda chain. One can obtain various solutions of the twisted Yang-Baxter and star-triangle relations by calculating the intertwiners of the representations of the algebras of monodromy matrices at roots of unity for other trigonometric and elliptic $R$-matrices.

## §1. Basic definitions

Let $U$ be a complex manifold, $\mu: U \times U \rightarrow U \times U$ be a birational automorphism of $U \times U$. We will use a notation: $\mu(u, v)=(\varphi(u, v), \psi(u, v))$ where $u, v \in U$. Here $\varphi$ and $\psi$ are meromorphic functions from $U \times U$ to $U$.

Let us introduce the following birational automorphisms of $U \times U \times U: \sigma_{1}=\mu \times \mathrm{id}$ and $\sigma_{2}=\mathrm{id} \times \mu$. We have: $\sigma_{1}(u, v, w)=(\varphi(u, v), \psi(u, v), w)$ and $\sigma_{2}(u, v, w)=$ $(u, \varphi(v, w), \psi(v, w))$.

Definition We call a map $\mu$ a twisted transposition if the automorphisms $\sigma_{1}$ and $\sigma_{2}$ satisfy the following relations:

$$
\begin{equation*}
\sigma_{1}^{2}=\sigma_{2}^{2}=\mathrm{id}, \sigma_{1} \sigma_{2} \sigma_{1}=\sigma_{2} \sigma_{1} \sigma_{2} \tag{1}
\end{equation*}
$$

If $\mu$ is a twisted transposition, then for each $N \in \mathbb{N}$ we have a birational action of the symmetric group $S_{N}$ on the manifold $U^{N}$ such that the transposition $(i, i+1)$ acts by an automorphism $\sigma_{i}=\mathrm{id}^{i-1} \times \mu \times \mathrm{id}^{N-i-1}$. So we have $\sigma_{i}\left(u_{1}, \ldots, u_{N}\right)=\left(u_{1}, \ldots, \varphi\left(u_{i}, u_{i+1}\right), \psi\left(u_{i}, u_{i+1}\right), \ldots, u_{N}\right)$. It is clear that the relations (1) are equivalent to the defining relations in the group $S_{N}: \sigma_{i}^{2}=e, \sigma_{i} \sigma_{i+1} \sigma_{i}=$ $\sigma_{i+1} \sigma_{i} \sigma_{i+1}, \sigma_{i} \sigma_{j}=\sigma_{j} \sigma_{i}$ for $|i-j|>1$.

It is easy to check that the relations (1) are equivalent to the following functional equations for $\varphi$ and $\psi$ :

$$
\begin{gather*}
\varphi(\varphi(u, v), \psi(u, v))=u, \psi(\varphi(u, v), \psi(u, v))=v \\
\varphi(u, \varphi(v, w))=\varphi(\varphi(u, v), \varphi(\psi(u, v), w)) \\
\varphi(\psi(u, \varphi(v, w)), \psi(v, w))=\psi(\varphi(u, v), \varphi(\psi(u, v), w))  \tag{2}\\
\psi(\psi(u, v), w)=\psi(\psi(u, \varphi(v, w)), \psi(v, w))
\end{gather*}
$$

Remarks 1. From (2) it follows that for each $N$ the functions $\varphi\left(u_{1}, \varphi\left(u_{2}, \ldots, \varphi\left(u_{N}, w\right) \ldots\right)\right.$ and $\psi\left(\ldots\left(\psi\left(w, u_{1}\right), u_{2}\right) \ldots, u_{N}\right)$ are invariant with respect to the action of the group $S_{N}$ on the variables $u_{1}, \ldots, u_{N}$.
2. Let $\sigma: U \times U \rightarrow U \times U$ be the map given by $\sigma(u, v)=(v, u)$. Then $\sigma \mu$ is a set-theoretical solution to the quantum Yang-Baxter relation.
3. Informally one can consider $\sigma \mu$ as an infinite dimensional $R$-matrix in the space of functions. Namely, if we consider the space of meromorphic functions $\{f$ : $U \times U \rightarrow \mathbb{C}\}$ as an "extended tensor square" of the space of meromorphic functions $\{f: U \rightarrow \mathbb{C}\}$, then the linear operator $R_{\sigma \mu}: f \rightarrow f \sigma \mu$ (that is $R_{\sigma \mu} f(u, v)=$ $f(\sigma(\mu(u, v))))$ satisfies the usual Yang-Baxter relation.

Examples 1. Let $q, q^{-1}: U \rightarrow U$ be birational automorphisms such that $q q^{-1}=q^{-1} q=\mathrm{id}$. Then

$$
\mu(u, v)=\left(q(v), q^{-1}(u)\right)
$$

is a twisted transposition.
2. Let $U=\mathbb{C}$, then the following formula gives a twisted transposition:

$$
\mu(u, v)=\left(1-u+u v, \frac{u v}{1-u+u v}\right)
$$

3. Let $U$ be a finite dimensional associative algebra with a unity $1 \in U$, for example $U=\mathrm{Mat}_{m}$. Then the following formula gives a twisted transposition:

$$
\mu(u, v)=\left(1-u+u v,(1-u+u v)^{-1} u v\right)
$$

Let $V$ be a $n$-dimensional vector space. For each $u \in U$ we denote by $V(u)$ a vector space canonically isomorphic to $V$. Let $R$ be a meromorphic function from $U \times U$ to $\operatorname{End}(V \otimes V)$. We will consider $R(u, v)$ as a linear operator

$$
R(u, v): V(u) \otimes V(v) \rightarrow V(\varphi(u, v)) \otimes V(\psi(u, v))
$$

Definition We call $R$ a twisted $R$-matrix (with respect to the twisted transposition $\mu$ ) if it satisfies the following properties:

1. The composition

$$
V(u) \otimes V(v) \rightarrow V(\varphi(u, v)) \otimes V(\psi(u, v)) \rightarrow V(u) \otimes V(v)
$$

is equal to the identity, that is $R(\varphi(u, v), \psi(u, v)) R(u, v)=1$.
2. The following diagram is commutative:

$$
\begin{aligned}
& V(\varphi(u, v)) \otimes V(\psi(u, v)) \otimes V(w) \xrightarrow{1 \otimes R(\psi(u, v), w)}(\varphi(u, v)) \otimes V(\varphi(\psi(u, v)), w)) \otimes V(\psi(\psi(u, v), w)) \\
& \uparrow_{R(u, v) \otimes 1} \\
& V(u) \otimes V(v) \otimes V(w) \\
& \downarrow 1 \otimes R(v, w) \\
& V(u) \otimes V(\varphi(v, w)) \otimes V(\psi(v, w)) \xrightarrow{R}) \xrightarrow{u, \varphi(v, w)})^{\Downarrow}(\varphi(u, \varphi(v, w))) \otimes V(\psi(u, \varphi(v, w))) \otimes V(\psi(v, w))
\end{aligned}
$$

Here $\widetilde{V}=V(\varphi(u, \varphi(v, w))) \otimes V(\psi(\varphi(u, v), \varphi(\psi(u, v), w))) \otimes V(\psi(\psi(u, v), w))$.
In other words,

$$
\begin{align*}
& \left.R^{12}(\varphi(u, v), \varphi(\psi(u, v), w))\right) R^{23}(\psi(u, v), w) R^{12}(u, v)= \\
& R^{23}(\psi(u, \varphi(v, w)), \psi(v, w)) R^{12}(u, \varphi(v, w)) R^{23}(v, w) \tag{3}
\end{align*}
$$

Here $R^{12}=R \otimes 1$ and $R^{23}=1 \otimes R$ are linear operators in $V \otimes V \otimes V$.
We call (3) a twisted Yang-Baxter relation.

Let $\left\{x_{i}, i=1 \ldots, n\right\}$ be a basis of the linear space $V,\left\{x_{i}(u)\right\}$ be the corresponding basis of the linear space $V(u)$. It is clear that the following two linear operators are twisted $R$-matrices for each $\mu$ :

$$
\begin{aligned}
& x_{i}(u) \otimes x_{j}(v) \rightarrow x_{i}(\varphi(u, v)) \otimes x_{j}(\psi(u, v)) \\
& x_{i}(u) \otimes x_{j}(v) \rightarrow x_{j}(\varphi(u, v)) \otimes x_{i}(\psi(u, v))
\end{aligned}
$$

## $\S 2$. Set-theoretical solution from factorization of matrix polynomials

For the general theory of matrix polynomials and factorizations see [7]. For our purposes we state results, which may be well known to the experts.

We denote by $S(a)$ the set of eigenvalues of a matrix $a \in M a t_{m}$. More generally, we denote by $S\left(a_{1}, \ldots, a_{d}\right), a_{1}, \ldots, a_{d} \in M a t_{m}$, the set of roots of a polynomial $f(t)=\operatorname{det}\left(t^{d}-a_{1} t^{d-1}+\cdots+(-1)^{d} a_{d}\right)$. We will consider polynomials with generic coefficients only, so $\# S\left(a_{1}, \ldots, a_{d}\right)=m d$.

Proposition 1. Let

$$
\begin{equation*}
t^{d}-a_{1} t^{d-1}+\cdots+(-1)^{d} a_{d}=\left(t-b_{1}\right) \ldots\left(t-b_{d}\right) \tag{4}
\end{equation*}
$$

for generic matrices $a_{1}, \ldots, a_{d} \in M a t_{m}$, then $S\left(b_{i}\right) \cap S\left(b_{j}\right)=\emptyset$ for $i \neq j$ and $S\left(b_{1}\right) \cup \cdots \cup S\left(b_{d}\right)=S\left(a_{1}, \ldots, a_{d}\right)$. For each decomposition $S\left(a_{1}, \ldots, a_{d}\right)=A_{1} \cup$ $\cdots \cup A_{d}$, such that $\# A_{i}=m, A_{i} \cap A_{j}=\emptyset(i \neq j)$ there exists a unique factorization (4) with $S\left(b_{i}\right)=A_{i}$.

Proof The first statement follows from the equation $\operatorname{det}\left(t^{d}-a_{1} t^{d-1}+\cdots+\right.$ $\left.(-1)^{d} a_{d}\right)=\operatorname{det}\left(t-b_{1}\right) \ldots \operatorname{det}\left(t-b_{d}\right)$.

On the other hand, if we know eigenvalues of $b_{1}, \ldots, b_{d}$ then we can calculate eigenvectors of them. For $\lambda \in S\left(b_{d}\right)$ the corresponding eigenvector is a vector $v_{\lambda}$, such that $\left(\lambda^{d}-a_{1} \lambda^{d-1}+\cdots+(-1)^{d} a_{d}\right) v_{\lambda}=0$. If we know all eigenvectors of $b_{d}$, then we can calculate all eigenvectors of $b_{d-1}$ similarly and so on. This implies the uniqueness. By our construction of $b_{1}, \ldots, b_{d}$ the determinants of the matrix polynomials in the right hand side and the left hand side of (4) have the same sets of roots. Moreover, for each root $\lambda$ the operators represented by these matrix polynomials have the same kernel if we set $t=\lambda$. It implies that these polynomials are equal.

Proposition 2. Let $a_{1}, a_{2} \in M a t_{m}$ be generic matrices. Then there exists a unique pair of matrices $b_{1}, b_{2} \in M a t_{m}$ such that $\left(t-a_{1}\right)\left(t-a_{2}\right)=\left(t-b_{1}\right)\left(t-b_{2}\right)$ and $S\left(b_{1}\right)=S\left(a_{2}\right), S\left(b_{2}\right)=S\left(a_{1}\right)$. We have $b_{1}=a_{1}+\Lambda^{-1}, b_{2}=a_{2}-\Lambda^{-1}$ where $a_{2} \Lambda-\Lambda a_{1}=1$.

Proof If $S\left(b_{2}\right) \cap S\left(a_{2}\right) \neq \emptyset$, then $\operatorname{det}\left(a_{2}-b_{2}\right)=0$, because $a_{2}$ and $b_{2}$ have a common eigenvector. Otherwise, we can put $\Lambda=\left(a_{2}-b_{2}\right)^{-1}$.

Let $U=M a t_{m}$. From the propositions 1 and 2 it follows that the formula $\mu\left(a_{1}, a_{2}\right)=\left(b_{1}, b_{2}\right)$ gives a twisted transposition, where $b_{1}+b_{2}=a_{1}+a_{2}, b_{1} b_{2}=$ $a_{1} a_{2}, S\left(b_{1}\right)=S\left(a_{2}\right), S\left(b_{2}\right)=S\left(a_{1}\right)$. We have $\mu\left(a_{1}, a_{2}\right)=\left(a_{1}+\Lambda^{-1}, a_{2}-\Lambda^{-1}\right)$, where $\Lambda$ is the solution of the linear matrix equation $a_{2} \Lambda-\Lambda a_{1}=1$.

Let $\bar{U}=\overline{M a t_{m}}$ be the set of $m \times m$ matrices with different eigenvalues and fixed order of eigenvalues. The proposition 1 gives an action of the symmetric group $S_{m N}$ on the space $\bar{U}^{N}$ by birational automorphisms. By definition, for $\sigma \in S_{m N}$, $b_{1}, \ldots, b_{N} \in \bar{U}$ we have $\sigma\left(b_{1}, \ldots, b_{N}\right)=\left(b_{1}^{\prime}, \ldots, b_{N}^{\prime}\right)$ where $\left(t-b_{1}\right) \ldots\left(t-b_{N}\right)=$ $\left(t-b_{1}^{\prime}\right) \ldots\left(t-b_{N}^{\prime}\right)$ and $\bar{S}\left(b_{i}^{\prime}\right)=\sigma \bar{S}\left(b_{i}\right), \bar{S}$ stands for the ordered set of eigenvalues.

This action is local in the following sense. The transposition $(i, i+1)$ for $\alpha m<$ $i<(\alpha+1) m$ acts only inside the $\alpha+1$-th factor of $\bar{U}^{N}$ and the transposition $(\alpha m, \alpha m+1)$ acts only inside the product of the $\alpha$-th and the $\alpha+1$-th factors. We have also the twisted transposition $\mu: \bar{U} \times \bar{U} \rightarrow \bar{U} \times \bar{U}$ in this case which is the action of the element $(1, m+1)(2, m+2) \ldots(m-1,2 m-1) \in S_{2 m}$.

Remark Let $U$ be the set of matrix polynomials of the form $a t+b$, where $a, b \in M a t_{m}, a=\left(a_{i j}\right), b=\left(b_{i j}\right)$ and $a_{i j}=0$ for $i<j, b_{i j}=0$ for $i>j$. It is possible to define a twisted transposition $\mu$ such that for $\mu(f(t), g(t))=\left(f_{1}(t), g_{1}(t)\right)$ we have $f(t) g(t)=f_{1}(t) g_{1}(t)$, $\operatorname{det} f(t)$ and det $g_{1}(t)$ have the same sets of roots and the first coefficients of $f(t)$ and $g_{1}(t)$ have the same diagonal elements. In [4] we found the solutions of the corresponding twisted Yang-Baxter relation (for $m=2$ ), which is a generalization of the $R$-matrix from chiral Potts model.

## $\S 3$. Set-theoretical solution from factorization of matrix $\theta$-functions

Let $\Gamma \subset \mathbb{C}$ be a lattice generated by 1 and $\tau$ where $\operatorname{Im} \tau>0$. We have $\Gamma=$ $\{\alpha+\beta \tau ; \alpha, \beta \in \mathbb{Z}\}$. Let $\varepsilon \in \mathbb{C}$ be a primitive root of unity of degree $m$. Let $\gamma_{1}, \gamma_{2} \in M a t_{m}$ be $m \times m$ matrices such that $\gamma_{1}^{m}=\gamma_{2}^{m}=1, \gamma_{2} \gamma_{1}=\varepsilon \gamma_{1} \gamma_{2}$. We have $\gamma_{1} v_{\alpha}=\varepsilon^{\alpha} v_{\alpha}, \gamma_{2} v_{\alpha}=v_{\alpha+1}$ in some basis $\left\{v_{\alpha} ; \alpha \in \mathbb{Z} / m \mathbb{Z}\right\}$ of $\mathbb{C}^{m}$. Let us assume that $\left\{v_{1}, \ldots, v_{m}\right\}$ is the standard basis of $\mathbb{C}^{m}$.

We denote by $M \Theta_{n, m, c}(\Gamma)$ for $n, m \in \mathbb{N}, c \in \mathbb{C}$ the space of everywhere holomorphic functions $f: \mathbb{C} \rightarrow M a t_{m}$, which satisfy the following equations:

$$
\begin{gather*}
f\left(z+\frac{1}{m}\right)=\gamma_{1}^{-1} f(z) \gamma_{1} \\
f\left(z+\frac{1}{m} \tau\right)=e^{-2 \pi i(m n z-c)} \gamma_{2}^{-1} f(z) \gamma_{2} \tag{5}
\end{gather*}
$$

Proposition 3. $\operatorname{dim} M \Theta_{n, m, c}(\Gamma)=m^{2} n$ and for each element $f \in M_{n, m, c}(\Gamma)$ the equation $\operatorname{det} f(z)=0$ has exactly mn zeros modulo $\frac{1}{m} \Gamma$. The sum of these zeros is equal to $m c+\frac{m n}{2}$ modulo $\Gamma$.

Proof For $m=1$ we have the usual $\theta$-functions $\Theta_{n, c}(\Gamma)=M \Theta_{n, 1, c}(\Gamma)$ and all these statements are well known in this case ([8]). One has a basis $\left\{\theta_{\alpha}(z) ; \alpha \in\right.$ $\mathbb{Z} / n \mathbb{Z}\}$ in the space $\Theta_{n, c}(\Gamma)$ such that $\theta_{\alpha}\left(z+\frac{1}{n}\right)=e^{2 \pi i \frac{\alpha}{n}} \theta_{\alpha}(z), \theta_{\alpha}\left(z+\frac{1}{n} \tau\right)=$ $e^{-2 \pi i\left(z-\frac{n-1}{2 n} \tau-\frac{1}{n} c\right)} \theta_{\alpha+1}(z)([8])$. From (5) it follows that $f(z+1)=f(z)$ and $f(z+\tau)=e^{-2 \pi i\left(m^{2} n z-c_{1}\right)} f(z)$ for some $c_{1} \in \mathbb{C}$. So the matrix elements of $f(z)$ are $\theta$-functions from the space $\Theta_{m^{2} n, c_{1}}(\Gamma)$. We have decomposition $f(z)=$ $\sum_{\alpha} \varphi_{\alpha} \theta_{\alpha}(z)$, where $\varphi_{\alpha} \in M a t_{m}$ are constant matrices, $\left\{\theta_{\alpha}\right\}$ is a basis in the space $\Theta_{m^{2} n, c_{1}}(\Gamma)$. Substituting this decomposition in (6) one can calculate the dimension of the space $M \Theta_{n, m, c}(\Gamma)$. We have also $\operatorname{det} f\left(z+\frac{1}{m}\right)=\operatorname{det} f(z)$ and $\operatorname{det} f\left(z+\frac{1}{m} \tau\right)=e^{-2 \pi i\left(m^{2} n z-m c\right)} \operatorname{det} f(z)$. From this follows the statement about zeros of the equation $\operatorname{det} f(z)=0$.

Proposition 4. For generic complex numbers $\lambda_{1}, \ldots, \lambda_{m n}$ such that $\lambda_{1}+\cdots+$ $\lambda_{m n} \equiv m c+\frac{m n}{2} \bmod \frac{1}{m} \Gamma$ and nonzero vectors $v_{1}, \ldots, v_{m n} \in \mathbb{C}^{m}$ there exists a unique up to proportionality element $f(z) \in M \Theta_{n, m, c}(\Gamma)$ such that $\operatorname{det} f\left(\lambda_{\alpha}\right)=$ $0, f\left(\lambda_{\alpha}\right) v_{\alpha}=0$ for $1 \leqslant \alpha \leqslant m n$.

Proof Considering the decomposition $f(z)=\sum_{\alpha} \varphi_{\alpha} \theta_{\alpha}(z)$, one has the system of linear equations $\left\{\sum_{\alpha} \theta_{\alpha}\left(\lambda_{\beta}\right) \varphi_{\alpha} v_{\beta}=0 ; \beta=1, \ldots, m n\right\}$ for matrix elements of $\left\{\varphi_{\alpha}\right\}$. One can see that this system defines $\left\{\varphi_{\alpha}\right\}$ uniquely up to proportionality for generic $\lambda_{1}, \ldots, \lambda_{m n}, v_{1}, \ldots, v_{m n}$.

We denote by $S(f)$ the set of zeros of the equation $\operatorname{det} f(z)=0$ modulo $\frac{1}{m} \Gamma$.
Proposition 5. Assume that $f(z) \in M \Theta_{n, m, c}(\Gamma)$ is a generic element and we have a factorization $f(z)=f_{1}(z) \ldots f_{n}(z)$, where $f_{\alpha}(z) \in M \Theta_{1, m, c_{\alpha}}(\Gamma), c_{1}+\cdots+$ $c_{n}=c$. Then $S\left(f_{\alpha}\right) \cap S\left(f_{\beta}\right)=\emptyset$ for $\alpha \neq \beta$ and $S(f)=S\left(f_{1}\right) \cup \cdots \cup S\left(f_{n}\right)$. For each decomposition $S(f)=A_{1} \cup \cdots \cup A_{n}$ such that $A_{\alpha} \cap A_{\beta}=\emptyset$ for $\alpha \neq \beta$ and $\# A_{\alpha}=m$
there exists a unique factorization $f(z)=f_{1}(z) \ldots f_{n}(z)$ up to proportionality of $f_{\alpha}$ such that $S\left(f_{\alpha}\right)=A_{\alpha}$ for $\alpha=1, \ldots, n$.

Proof is similar to the proof of the proposition 1, we just change polynomials by $\theta$-functions.

Let $U_{c}$ be the projectivisation of the linear space $M \Theta_{1, m, c}(\Gamma)$ and $U=\bigcup_{c \in \mathbb{C}} U_{c}$. We have the following twisted transposition $\mu: U \times U \rightarrow U \times U$. By definition $\mu(f, g)=\left(f_{1}, g_{1}\right)$, where $f(z) g(z)=f_{1}(z) g_{1}(z)$ and $S\left(f_{1}\right)=S(g), S\left(g_{1}\right)=S(f)$.

Let $\bar{U}$ be the set of elements $f$ from $U$ with a fixed order on $S(f)$. For $f \in \bar{U}$ let $\bar{S}(f)$ be the set $S(f)$ with corresponding order. We have a local action of the symmetric group $S_{m N}$ on the space $\bar{U}^{N}$. By definition, for $\sigma \in S_{m N}$ we have $\sigma\left(f_{1}, \ldots, f_{N}\right)=\left(f_{1}^{\sigma}, \ldots, f_{N}^{\sigma}\right)$ where $f_{1}(z) \ldots f_{N}(z)=f_{1}^{\sigma}(z) \ldots f_{N}^{\sigma}(z)$ and $\bar{S}\left(f_{\alpha}^{\sigma}\right)=$ $\sigma \bar{S}\left(f_{\alpha}\right)$ for $1 \leqslant \alpha \leqslant N$.

Remark It is possible to construct twisted $R$-matrices for this twisted transposition $\mu$ as intertwiners of tensor products of cyclic representations of the algebra of monodromy matrices for the elliptic Belavin $R$-matrix [5] at the point of finite order (see also [6]). It will be the subject of another paper.

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